# Matrix-wise $\ell_0$ -constrained Sparse Nonnegative Least Squares

Sparse Days 2022

<u>Nicolas Nadisic</u>, Jeremy E Cohen, Arnaud Vandaele, Nicolas Gillis 22 June 2022

Université de Mons, Belgium

High-level motivations:

- Extract underlying structures in data
- Better leverage a priori knowledge, here nonnegativity and sparsity, to improve models
- Develop algorithms that are both guaranteed and computationally tractable

Focus of this work: linear models of the form

 $B \approx AX$ ,

where

- *B* ∈ ℝ<sup>m×n</sup> is the data/input matrix, representing measures or observations,
- A ∈ ℝ<sup>m×r</sup> is a coeficient matrix, called dictionary, representing features, atoms, or components.
- $X \in \mathbb{R}^{r \times n}$  is a signal or information matrix,
- $r \ll \min(m, n)$

# One application — Hyperspectral unmixing

B(:,j)spectral signature of j-th pixel



Images from Bioucas Dias and Nicolas Gillis.

## One application — Hyperspectral unmixing



Images from Bioucas Dias and Nicolas Gillis.

## Linear mixing model



#### Linear mixing model



Nonnegativity constraint:

- Assumes data is generated from an additive linear combination of features
- Natural in this application
- Produces more interpretable factors

#### Multiple Nonnegative Least Squares (MNNLS) problem

$$\min_{\mathbf{X} \ge 0} \|B - A\mathbf{X}\|_F^2$$

#### Multiple Nonnegative Least Squares (MNNLS) problem

$$\min_{\mathbf{X}\geq 0} \|B - A\mathbf{X}\|_F^2$$

#### Can be divided in *n* independent NNLS subproblems,

$$\min_{\substack{\mathbf{X}(:,j) \ge 0}} \|B(:,j) - A\mathbf{X}(:,j)\|_2^2$$
$$\Leftrightarrow \min_{\substack{\mathbf{x} \ge 0}} \|b - A\mathbf{x}\|_2^2$$

Given *B* and *A*, find  $X \ge 0$ 





 $\times$ 

 $X \ge 0$ 



# Sparsity — Why?

- Regularize the problem
- Better interpretability
- Natural in many applications  $\Rightarrow$  leverage a-priori knowledge to improve the model



# Sparsity in hyperspectral unmixing

 $\approx$ 







spectral signature of p-th material abundance of p-th material in j-th pixel







The classical way:  $\ell_1$  penalty

$$\min_{\mathbf{X} \ge 0} \|B - A\mathbf{X}\|_F^2 + \lambda \|X\|_1$$

Issues:

- Restrictive condititions for support recovery
- Parameter  $\lambda$  is hard to tune, no physical meaning

More intuitive formulation: column-wise k-sparsity constraint ( $\ell_0$ -"norm",  $||x||_0 = |\{i : x_i \neq 0\}|$ )

$$\min_{\boldsymbol{X} \ge 0} \|\boldsymbol{B} - \boldsymbol{A}\boldsymbol{X}\|_2^2 \text{ s.t. } \|\boldsymbol{X}(:,j)\|_0 \le k \text{ for all } j$$

Issue:

• What if the relevant k varies between column?

#### Matrix-wise q-sparse MNNLS

$$\min_{X \ge 0} \|B - AX\|_F^2 \quad \text{s.t.} \quad \|X\|_0 \le q$$

- Can be seen as a global sparsity budget
- If  $q = k \times n$ , this enforces an average k-sparsity on the columns of X

#### Matrix-wise q-sparse MNNLS

$$\min_{X \ge 0} \|B - AX\|_F^2 \quad \text{s.t.} \quad \|X\|_0 \le q$$

- Can be seen as a global sparsity budget
- If  $q = k \times n$ , this enforces an average k-sparsity on the columns of X

How to solve it?

- With a *k*-sparse NNLS methods, by vectorizing the problem
   ⇒ leads to a huge NNLS problem, too expensive to solve
- Our contribution: dedicated algorithm

$$\begin{split} \min_{\substack{H \ge 0}} \|M - WH\|_2^2 \text{ s.t. } \|H\|_0 &\leq q \\ \Rightarrow \text{ vectorize} \\ \min_{\substack{h \ge 0}} \|m - \Omega h\|_2^2 \text{ s.t. } \|h\|_0 &\leq q \\ \end{split}$$
where  $\Omega = W \otimes I \in \mathbb{R}^{(m.n) \times (r.n)} \text{ and } m = \begin{bmatrix} M(:,1) \\ M(:,2) \\ \vdots \\ M(:,n) \end{bmatrix} \in \mathbb{R}^{(m.n)}$ 

Algorithm Salmon<sup>1</sup>:

- 1. Generate a set of solutions for every column of *X*, with different tradeoffs between reconstruction error and sparsity
  - Divide the sparse MNNLS problem into *n* biobjective sparse NNLS subproblems

$$\min_{X(:,j)\geq 0} \{ \|B(:,j) - AX(:,j)\|_2^2 , \|X(:,j)\|_0 \}$$

- Solve with branch-and-bound, or heuristic (homotopy, greedy algo)
- Build a cost matrix C

<sup>&</sup>lt;sup>1</sup>Salmon Applies  $\ell_0$ -constraints Matrix-wise On NNLS problems

Algorithm Salmon<sup>1</sup>:

- 1. Generate a set of solutions for every column of *X*, with different tradeoffs between reconstruction error and sparsity
  - Divide the sparse MNNLS problem into *n* biobjective sparse NNLS subproblems

$$\min_{X(:,j)\geq 0} \{ \|B(:,j) - AX(:,j)\|_2^2 , \|X(:,j)\|_0 \}$$

- Solve with branch-and-bound, or heuristic (homotopy, greedy algo)
- Build a cost matrix C
- 2. Select one solution per column such that in total X has q nonzero entries and the error is minimized  $\Rightarrow$  assignment-like problem
  - Dedicated greedy algorithm proved near-optimal

<sup>&</sup>lt;sup>1</sup>Salmon Applies  $\ell_0$ -constraints Matrix-wise On NNLS problems

$$\min_{\mathbf{x}\geq 0} \begin{cases} \|A\mathbf{x} - b\|_2^2\\ \|\mathbf{x}\|_0 \end{cases}$$

Equivalent to  $\min_{\substack{x \ge 0}} \|b - Ax\|_2^2$  s.t.  $\|x\|_0 \le k$  for all  $k \in \{0, \dots, r\}$ 

#### Salmon — Step 1: Pareto front



- Each row = one sparsity level
- Each column = one column of the MNNLS problem

$$\begin{pmatrix} C_{0,1} & C_{0,2} & \cdots & C_{0,n} \\ C_{1,1} & C_{1,2} & \cdots & C_{1,n} \\ \vdots & \vdots & \ddots & \vdots \\ C_{r,1} & C_{r,2} & \cdots & C_{r,n} \end{pmatrix}$$

 $C(i,j) \approx \min_{x \ge 0} \|B(:,j) - Ax\|_2^2 \text{ s.t. } \|x\|_0 \le i$ 













#### Salmon — Step 2: Select one solution per column

Similar to an assignment problem

$$\begin{pmatrix} C_{0,1} & C_{0,2} & \cdots & C_{0,n} \\ C_{1,1} & C_{1,2} & \cdots & C_{1,n} \\ \vdots & \vdots & \ddots & \vdots \\ C_{r,1} & C_{r,2} & \cdots & C_{r,n} \end{pmatrix}$$

Let  $z_{i,j} \in \{0,1\}$  such that  $z_{i,j} = 1$  if and only if the *j*th column of X is *i*-sparse,

$$\begin{split} \min_{z \in \{0,1\}^{r \times n}} \sum_{i,j} z_{i,j} \mathcal{C}(i,j) \\ \text{such that } \sum_{i} z_{i,j} = 1 \text{ for all } j, \text{ and } \sum_{i,j} i z_{i,j} \leq q \end{split}$$

Solved with a dedicated greedy algorithm, fast but proved near-optimal





 $\|X\|_0=0$ 





 $\|X\|_{0} = 1$ 

20/26





 $||X||_0 = 2$ 





 $||X||_0 = 3$ 





 $||X||_0 = 5$ 





$$||X||_0 = 5$$

Iterate while  $||X||_0 < q$ 



Final solution X, q-sparse matrix

$$X \approx \arg\min_{X \ge 0} \|B - AX\|_F^2$$
 s.t.  $\|X\|_0 \le q$ 

In short:

- The worst case is not too bad (wrong support in at most one column)
- In practice, often optimal (19 out of 22 cases in our xp)

In short:

- The worst case is not too bad (wrong support in at most one column)
- In practice, often optimal (19 out of 22 cases in our xp)

Intuition of the proof:

- The objective function is separable by columns
- At each iteration, we maximize the global decrease in error





#### One experiment: unmixing of hyperspectral image Jasper



NNLS (no sparse)





Salmon, q/n = 2

Salmon, q/n = 1.8

- We introduced a sparse MNNLS model with matrix-wise  $\ell_0\mbox{-sparsity}$  constraint
- We developed a two-step algorithm to tackle it
- Makes tractable some problems that are too big for standard NNLS solvers
- Improves results, allows a finer parameter tuning
- Interesting where sparsity varies between columns

# Thanks!

Contact: nicolas.nadisic@umons.ac.be

Paper and code:

http://nicolasnadisic.xyz

$$\min_{X>0} \|B - AX\|_F^2 \quad \text{s.t.} \quad \|X\|_0 \le q$$

